Co-segmentation Inspired Attention Module for Video-based Vision tasks

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Computer Vision Lab, IIT Madras

Seminar-II

December 16, 2021

1/46

Introduction to Person Re-Identification

• Person Re-ID: Task definition

Ourrent task

- Problem statement
- Co-segmentation Activation Module (COSAM)
- Video-based person re-ID
- Comparison with Non-local Blocks
- Qualitative visualization
- Extending to Video classification task

Summary

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Person Re-Identification Problem definition

- A fine-grained retrieval task to match a person's image with images from database
- images captured at
 - same/different points in time (of same day)
 - same/different camera
 - various lighting conditions + unconstrained viewpoint/pose changes
- No information about camera position, intrinsic and extrinsic parameters



Image from: Apurva et al. A survey of approaches and trends in person re-identification. Image and Vision Computing - 2014.

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Person Re-Identification setup

- **Probe:** the person's image(s) to be searched in the database
- Gallery: one (or more) unique image(s) of persons observed so far. Usually, Gallery images will be available in a database.



• Evaluation: Ranking of matching scores (rank-1, rank-5, ...), mean average precision (mAP)

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Practical challenges

- Illumination variation
- Pose/Viewpoint variation
- Background clutters / misalignment errors
- Partial occlusion
- Bad quality images



Viewpoint Change



Illumination Variation



Partial Occlusion



(a)



Poor quality of images



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Seminar-II: Background clutter / Misalignment errors



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Problem statement

Seminar-II: Background clutter / Misalignment errors



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Problem statement

Seminar-II: Background clutter / Misalignment errors



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Problem statement

Seminar-II: Background clutter / Misalignment errors



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Co-segmentation concept



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Co-segmentation in Deep learning literature



^{*}MC = Mutual Correlation

Weihao Li, Omid Hosseini Jafari, and Carsten Rother. "Deep object co-segmentation." Asian Conference on Computer Vision. Springer, Cham, 2018.

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Co-segmentation in Deep learning literature



Hong Chen, Yifei Huang, and Hideki Nakayama. "Semantic aware attention based deep object co-segmentation." Asian Conference on Computer Vision. Springer, Cham, 2018.

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Co-segmentation Activation Module (COSAM)



Input $(N \times D \times H \times W) \rightarrow$ Induce co-segmentation \rightarrow Output $(N \times D \times H \times W)$

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Frames of dimension $N \times 3 \times H_I \times W_I$ are passed through *L* CNN blocks to get feature maps of dimension $N \times D \times H \times W$.

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Dimensionality reduction ($D \times H \times W \longrightarrow D_R \times H \times W$)

 $D \longrightarrow D_R$ - to reduce computational overhead

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$$NCC(P,Q) = \frac{1}{D_R} \frac{\sum_{k=1}^{D_R} (P_k - \mu_P) \cdot (Q_k - \mu_Q)}{\sigma_P \cdot \sigma_Q}$$
(2)

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- Pass cost volume through Conv + BN + ReLU \rightarrow Sigmoid to get spatial mask.
- Multiply spatial masks with corresponding feature maps

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- Per-frame Channel attention from Global Average Pool-ed (GAP) feature maps
- Average of per-frame channel attentions to capture common important channels

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Video Re-ID pipeline



Arulkumar Subramaniam, Athira Nambiar, and Anurag Mittal. Co-segmentation Inspired Attention Networks for Video-based Person Re-identification. Proceedings of the International Conference on Computer Vision (ICCV) - 2019.

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Video Re-ID datasets

MARS

- 1261 identities and 20,478 video sequences
- 6 non-overlapping cameras
- 625 identities for training and the rest for testing
- Additional 3,248 identities for distractors
- DukeMTMC-VideoReID
 - 702 identities each for training and testing
 - 369,656 tracklets for training, and 445,764 frames for testing
 - 402 identities for distractors
- iLIDs-VID
 - Small dataset
 - 300 persons each for training and testing

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Training loss function:

$$L = \sum_{i=1}^{B} \left\{ L_{CE} + \lambda L_{triplet}(I_i, I_{i_+}, I_{i_-}) \right\}$$
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COSAM at different levels

	COSAM		MA	RS		Duke	MTMC	-Videol	ReID
		mAP	R1	R5	R20	mAP	R1	R5	R20
R	No COSAM [1]	75.8	83.1	92.8	96.8	92.9	93.6	99.0	99.7
sNet	COSAM ₂	68.3	77.7	90.1	96.1	88.9	90.2	98.4	99.0
	COSAM ₃	76.9	82.7	94.3	97.3	93.6	94.0	98.7	99.9
ö	COSAM ₄	76.8	82.9	94.2	97.1	93.8	94.7	98.7	99.7
	COSAM ₅	76.6	82.8	93.9	97.2	93.2	93.7	98.4	99.9
	COSAM _{3,4}	76.4	83.4	93.9	97.1	93.7	94.4	99.1	99.4
	COSAM _{3,5}	76.9	83.7	94.0	97.3	93.0	93.7	99.0	99.7
	COSAM _{4,5}	77.2	83.7	94.1	97.5	94.0	94.4	99.1	99.9
	COSAM _{3,4,5}	76.6	83.2	93.7	97.3	93.1	93.6	98.7	99.4
	No COSAM	78.3	84.0	95.2	97.1	93.5	93.7	99.0	99.7
SE	COSAM ₂	67.0	77.9	90.4	94.9	92.2	94.0	98.9	99.7
-Re	COSAM ₃	79.5	85.0	94.7	97.8	93.6	94.7	99.0	99.9
Nŝ	COSAM ₄	79.8	84.9	95.4	97.8	94.0	95.4	99.0	99.9
let5	COSAM ₅	79.9	84.5	95.7	97.9	93.9	94.9	99.1	99.9
õ	COSAM _{3,4}	79.5	84.8	94.7	97.6	93.7	94.7	98.7	99.7
	COSAM _{3,5}	79.8	85.2	95.5	98.0	93.9	94.2	99.3	99.9
	COSAM _{4,5}	79.9	84.9	95.5	97.9	94.1	95.4	99.3	99.8
	COSAM _{3,4,5}	80.5	85.2	95.5	98.0	94.1	95.4	99.3	99.9

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COSAM at different levels

	COSAM		MA	RS		Duke	MTMC	-Videol	ReID
		mAP	R1	R5	R20	mAP	R1	R5	R20
Ъ	No COSAM [1]	75.8	83.1	92.8	96.8	92.9	93.6	99.0	99.7
٥s٨	COSAM ₂	68.3	77.7	90.1	96.1	88.9	90.2	98.4	99.0
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	COSAM ₅	76.6	82.8	93.9	97.2	93.2	93.7	98.4	99.9
	COSAM _{3,4}	76.4	83.4	93.9	97.1	93.7	94.4	99.1	99.4
	COSAM _{3,5}	76.9	83.7	94.0	97.3	93.0	93.7	99.0	99.7
	COSAM _{4,5}	77.2	83.7	94.1	97.5	94.0	94.4	99.1	99.9
	COSAM _{3,4,5}	76.6	83.2	93.7	97.3	93.1	93.6	98.7	99.4
	No COSAM	78.3	84.0	95.2	97.1	93.5	93.7	99.0	99.7
SE	COSAM ₂	67.0	77.9	90.4	94.9	92.2	94.0	98.9	99.7
-Re	COSAM ₃	79.5	85.0	94.7	97.8	93.6	94.7	99.0	99.9
NS	COSAM ₄	79.8	84.9	95.4	97.8	94.0	95.4	99.0	99.9
et5	COSAM ₅	79.9	84.5	95.7	97.9	93.9	94.9	99.1	99.9
õ	COSAM _{3,4}	79.5	84.8	94.7	97.6	93.7	94.7	98.7	99.7
	COSAM _{3,5}	79.8	85.2	95.5	98.0	93.9	94.2	99.3	99.9
	COSAM _{4,5}	79.9	84.9	95.5	97.9	94.1	95.4	99.3	99.8
	COSAM _{3,4,5}	80.5	85.2	95.5	98.0	94.1	95.4	99.3	99.9

Table: Evaluation of the backbone feature extractors with COSAM plugging in after in CNM block = > < = > = = <

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Quantitative results

COSAM with different temporal modeling schemes

	Temp.	COSAM	I	MARS			Duke		iLIDS-VID	
	Agg.	OOSAWi	mAP	R1	R5	mAP	R1	R5	R1	R5
	TP _{avg} [1]	-	75.8	83.1	92.8	92.9	93.6	99.0	73.9	92.6
Reg	TP _{avg}	$COSAM_{4,5}$	77.2	83.7	94.1	94.0	94.4	99.1	75.5	94.1
Ne	TA[1]	-	76.7	83.3	93.8	93.2	93.9	98.9	72.3	92.4
t50	TA	$COSAM_{4,5}$	76.9	83.6	93.7	93.4	94.6	98.9	74.9	94.4
	RNN[1]	-	73.8	81.6	92.8	88.1	88.7	97.6	68.5	93.2
	RNN	$COSAM_{4,5}$	74.8	82.4	93.9	90.4	91.7	98.3	68.9	93.1
	TD		70.4	04.0	05.0	00.5	00.7	00.0	70.0	00.0
	IP _{avg}	-	78.1	84.0	95.2	93.5	93.7	99.0	76.9	93.9
SE	TP _{avg}	$COSAM_{4,5}$	79.9	84.9	95.5	94.1	95.4	99.3	79.6	95.3
-Re	TA	-	77.7	84.2	94.7	93.1	94.2	99.0	74.7	93.2
Ne	TA	$COSAM_{4,5}$	79.1	85.0	94.9	94.1	95.3	98.9	77.1	94.7
et50	RNN	-	75.7	83.1	93.6	92.4	94.0	98.4	77.4	94.4
	RNN	$COSAM_{4,5}$	76.0	83.4	93.9	92.5	93.9	98.3	77.8	97.3

Table: Comparison of the baseline models with best performing COSAM-configuration (COSAM_{4,5}). Best mAP & CMC Rank-1 per backbone network are shown in **red** and **blue** colors respectively.

[1] Jiyang Gao, and Ram Nevatia. "Revisiting temporal modeling for video-based person reid." arXiv preprint arXiv:1805.02104 (2018).

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Comparison with State-of-the-arts

Network	Deep		MA	RS	
Network	model?	mAP	R1	R5	R20
TriNet	Yes	67.7	79.8	91.4	-
Region QEN	Yes	71.1	77.8	88.8	94.1
Comp. Snippet Sim.	Yes	69.4	81.2	92.1	-
Part-Aligned	Yes	72.2	83.0	92.8	96.8
RevisitTempPool	Yes	76.7	83.3	93.8	97.4
SE-ResNet50 + TP _{avg}	Yes	78.1	84.0	95.2	97.1
SE-ResNet50 + COSAM _{4,5}	Voc	70.0	94.0	05.5	07.0
+ TP _{avg} (ours)	165	79.9	04.9	95.5	97.9
SE-ResNet50 + COSAM _{4,5}	Voc	87 /	96 0	05.5	08.0
+ TP _{avg} (ours) + Re-ranking	163	07.4	00.5	33.5	30.0
Notwork	Deep	Du	keMTMC	-VideoR	eID
Network	model?	mAP	R1	R5	R20
ETAP-Net	Yes	78.34	83.62	94.59	97.58
RevisitTempPool	Yes	93.2	93.9	98.9	99.5
SE-ResNet50 + TP _{avg}	Yes	93.5	93.7	99.0	99.7
SE-ResNet50 + COSAM _{4,5} + TP _{avg} (ours)	Yes	94.1	95.4	99.3	99.8

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Method	i	iLIDS-VID					
Method	R1	R5	R20				
Top push video Re-ID	56.3	87.6	98.3				
JST-RNN	55.2	86.5	97.0				
Joint ST pooling	62.0	86.0	98.0				
Region QEN	77.1	93.2	99.4				
RevisitTempPool	73.9	92.6	98.41				
SE-ResNet50 + TP _{avg}	76.87	93.94	99.07				
SE-ResNet50 + COSAM _{4,5} + TP _{avg} (ours)	79.61	95.32	99.8				

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frame length		MA	RS		DukeMTMC-VideoReID			
	mAP	R1	R5	R20	mAP	R1	R5	R20
N = 2	78.1	83.5	94.3	98.1	94.0	94.3	99.1	99.9
N = 4	79.9	84.9	95.5	97.9	94.1	95.4	99.3	99.8
N = 8	77.4	84.6	94.2	97.0	92.1	91.9	99.0	99.6

Table: Evaluation of the influence of track length T on Re-ID performance in SE-ResNet50+COSAM_{4,5}+TP_{avg}.

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Model	Handbag				Hat		Backpack			
Model	mAP	R1	R5	mAP	R1	R5	mAP	R1	R5	
ResNet50+TP	91.2	92.0	100.0	91.1	91.7	97.5	92.8	93.9	98.6	
ResNet50+COSAM _{4,5} +TP	95.2	96.0	100.0	93.5	94.2	97.5	95.1	96.4	99.8	
SE-ResNet50+TP	94.1	97.3	100.0	92.7	94.2	99.2	94.3	95.6	99.1	
SE-ResNet50+COSAM _{4,5} +TP	96.0	100.0	100.0	93.9	96.7	99.5	95.4	97.1	100.0	

Table: Attribute-wise performance comparison on Duke dataset. TP = Temporal average pooling.

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	Train set	Test set	mAP	R1	R5	R20
No COSAM	MARS	DukeMTMC	32.0	33.3	53.3	67.1
COSAM _{4,5}	MARS	DukeMTMC	34.8	36.8	54.1	67.9
No COSAM	DukeMTMC	MARS	25.0	41.7	54.4	65.3
$COSAM_{4,5}$	DukeMTMC	MARS	25.9	42.4	56.0	65.8

Table: Cross-dataset performance of the best performing model with *SE-ResNet50* as the feature extractor and TP_{avg} as the temporal aggregation layer. Here *DukeMTMC* = DukeMTMC-VideoReID.

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Attention layer		MA	RS		DukeMTMC-VideoReID			
	mAP	R1	R5	R20	mAP	R1	R5	R20
Only spatial att.	78.8	84.1	94.9	97.7	93.6	93.9	99.0	99.9
Only Channel att.	79.0	84.3	95.0	97.8	93.8	94.4	99.1	997
Both	79.9	84.9	95.5	97.9	94.1	95.4	99.3	99.8

Table: Evaluation of the influence of Co-segmentation based attention layers on Re-ID performance of the best performing model SE-ResNet50+COSAM_{4,5}+ TP_{avg}.

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COSAM vs. Non-local Module (NLM)



Xiaolong Wang, et al. "Non-local neural networks." Proceedings of the IEEE conference on computer vision and pattern recognition. 2018.

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COSAM vs. Non-local Module (NLM)



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COSAM vs. Non-local Module (NLM)

	Module	#Params	#FLOPs	
_	Gauss.	4.2M	4.3B	
NLM	Gaussian embedding	8.39M	8.59G	
	Concatenation	8.4M	8.72G	
	Dot product	8.39M	8.59G	
	COSAM (ours)	1.6M	0.57G	

Table: COSAM vs. Non-local Module (input = $4 \times 2048 \times 16 \times 8$).

Observation: COSAM uses $\sim 4x$ less memory and $\sim 16x$ less computation than NLM.

Model	#Params	#FLOPs	MARS		
	, a a a a		mAP	R1	R5
ResNet50+NLM _{4,5} +TP	34.31M	27.11B	76.9	83.2	94.2
ResNet50+COSAM _{4,5} +TP	26.22M	17.24B	77.2	83.7	94.1
SE-ResNet50+NLM _{4,5} +TP	36.85M	26.74B	77.9	83.3	94.7
SE-ResNet50+COSAM _{4,5} +TP	28.76M	16.86B	79.9	84.9	95.5

Table: Comparison of COSAM vs. Non-local Module on MARS dataset.

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Qualitative visualization



Figure: Visualization of co-segmentations. The second row shows the segmentation maps corresponding to the images in the first row.

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Qualitative visualization

Qualitative visualization



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Extending to Video classification task

Extending to Video classification task



*FRMB = Feature Reduction with Modified Block

Training via simple cross-entropy loss:

$$L = -\sum_{k=1}^{N} \sum_{c=1}^{C} I(c = t_k) \log p_k^c$$
(4)

Here, I(.) denotes an indicator function, C = number of classes, N = number of videos, t_k = the target class one-hot vector, class softmax probabilities { p_k^j } $_{j=1}^C$.

[2] M. Esat Kalfaoglu, Sinan Kalkan, and A. Aydin Alatan. "Late temporal modeling in 3d cnn architectures with bert for action recognition." European Conference on Computer Vision. Springer, Cham, 2020.

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Working of BERT-CLS

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HMDB51

- 51 action categories
- total of 6,766 video clips extracted from movie scenes and YouTube.
- predefined split of train and test sequences

UCF101

- Total of 13220 videos belonging to 101 action classes
- average length of 180 frames per video
- predefined split of train and test sequences

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Backbone	COSAM2	temporal	#params	#Flons (G)	HMDB51		UCF101	
Dackbone	OCOAN	modeling?	(M)	#1 lops (G)	Top-1%	Top-3%	Top-1%	Top-3%
ResNeXt101 [2]	X	LSTM	47.6	38.64	73.68	87.46	93.90	98.05
ResNeXt101	1	LSTM	48.41	38.77	75.16	89.22	94.59	98.52
ResNeXt101 [2]	×	BERT	47.4	38.37	76.08	90.46	95.50	98.23
ResNeXt101	1	BERT	48.21	38.49	77.52	92.55	95.96	98.84
I3D [2]	×	BERT	13.57	110.6	68.63	87.78	92.50	98.26
I3D	1	BERT	14.23	110.7	69.38	87.95	93.05	98.63

Table: The performance comparison of single stream RGB model from [2] with and without COSAM layer.

[2] M. Esat Kalfaoglu, Sinan Kalkan, and A. Aydin Alatan. "Late temporal modeling in 3d cnn architectures with bert for action recognition." European Conference on Computer Vision. Springer, Cham, 2020.

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Quantitative results

Backbone	COSAM2	temporal	#params	#Flons (G)	HMDB51		UCF101	
Dackbone	COSAN	modeling?	(M)		Top-1%	Top-3%	Top-1%	Top-3%
ResNeXt101 [2]	×	LSTM	47.6	38.64	73.68	87.46	93.90	98.05
ResNeXt101	1	LSTM	48.41	38.77	75.16	89.22	94.59	98.52
ResNeXt101 [2]	×	BERT	47.4	38.37	76.08	90.46	95.50	98.23
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Backbone	COSAM2	temporal	#params	#Flons (G)	НМЕ	DB51	UCF	101
Dackbone	OCOAM	modeling?	(M)		Top-1%	Top-3%	Top-1%	Top-3%
ResNeXt101 [2]	×	LSTM	47.6	38.64	73.68	87.46	93.90	98.05
ResNeXt101	1	LSTM	48.41	38.77	75.16	89.22	94.59	98.52
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[2] M. Esat Kalfaoglu, Sinan Kalkan, and A. Aydin Alatan. "Late temporal modeling in 3d cnn architectures with bert for action recognition." European Conference on Computer Vision. Springer, Cham, 2020.

Backbone	COSAM2	temporal	#params	#Flons (G)	HMDB51		UCF101	
Dackbone	OOOAM:	modeling?	(M)		Top-1%	Top-3%	Top-1%	Top-3%
ResNeXt101 [2]	×	LSTM	47.6	38.64	73.68	87.46	93.90	98.05
ResNeXt101	✓	LSTM	48.41	38.77	75.16	89.22	94.59	98.52
ResNeXt101 [2]	X	BERT	47.4	38.37	76.08	90.46	95.50	98.23
ResNeXt101	✓	BERT	48.21	38.49	77.52	92.55	95.96	98.84
I3D [2]	×	BERT	13.57	110.6	68.63	87.78	92.50	98.26
I3D	✓	BERT	14.23	110.7	69.38	87.95	93.05	98.63

Table: The performance comparison of single stream RGB model from [2] with and without COSAM layer.

[2] M. Esat Kalfaoglu, Sinan Kalkan, and A. Aydin Alatan. "Late temporal modeling in 3d cnn architectures with bert for action recognition." European Conference on Computer Vision. Springer, Cham, 2020.

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State-of-the-art comparisons

	Method	use flow?	HMDB51	UCF101
	TwoStream	1	59.40	88.00
Ā	TwoStream Fusion + IDT	1	69.20	93.50
0-S	R(2+1)D	1	78.70	97.30
trea	I3D	1	80.90	97.80
am	BubbleNet	1	82.6	97.2
	ResNeXt101 BERT	1	83.55	97.87
(0)	IDT	×	61.70	-
ling	R(2+1)D	×	74.50	96.80
le-	MARS + RGB	×	73.10	95.60
stream	TemporalShift	×	73.50	95.90
	ResNeXt101 BERT	×	76.08	94.59
	ResNeXt101 + COSAM + BERT (ours)	×	77.52	95.96

Table: State-of-the-art performance comparison of deep models for video action classification task.

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	Method	use flow?	HMDB51	UCF101
	TwoStream	1	59.40	88.00
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Table: State-of-the-art performance comparison of deep models for video action classification task.

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Figure: "Sword Exercise" class from HMDB51 dataset

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Figure: "Hit" class from HMDB51 dataset

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Figure: "Horse Riding" class from UCF101 dataset

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Figure: "Playing Guitar" class from UCF101 dataset

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43/46

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- A "co-segmentation" inspired attention module (COSAM) to induce a notion of co-segmentation in feature space.
- COSAM is generic to be applied inside any deep CNN.
- Application to two video based vision tasks:
 - Video based person re-ID
 - Video classification
- Current work:
 - Self-supervised contrastive learning for person re-ID

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Thank you!

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45/46

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Co-segmentation inspired Attention Module

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